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SET-1

# III B.TECH – I SEM EXAMINATIONS, NOVEMBER - 2010 PROCESS CONTROL INSTRUMENTATION (COMMON TO EIE, ICE)

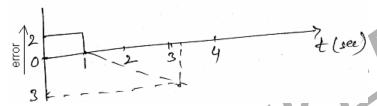
**Time: 3hours** 

Max.Marks:80

Answer any FIVE questions All questions carry equal marks

- - -

- 1. Name five flow laws relating to fluids, heat and electricity and state these laws. [16]
- 2.a) A proportional controller has a gain of 3. Plot the controller output for the error given below fig1. If  $P_0 = 50\%$ . [ $P_0$  controller output with no error]



b) With neat sketches, explain the principle of integral control action

[10+6]

- 3.a) Describe the output of a three mode controller for an assumed error variation. Discuss its features.
  - b) With an analytic expression of a PID control explain the effect of each mode on the output of the composite controller. [8+8]
- 4.a) Write a short note on following errors
  - i) IAE
- i) ITAI
- iii) ISE
- b) Explain the importance of 1/4<sup>th</sup> decay ratio.

[8+8]

- 5. Illustrate with relevant graphs. The following methods of optimum settings from the plant response
  - a) Damped Oscillation method
  - b) Reaction-curve method.

[16]

6. Explain the principle of a direct and reverse pneumatic actuator

[16]

- 7.a) Explain the flapper nozzle system with the help of its characteristic curves
  - b) Explain the following:
    - i) Quicle operating
    - ii) Linear
    - iii) Equal percentage characteristics of a control valve

[8+8]

8. Write the steps followed in choosing a valve for better control of flow and should be cost effective. [16]

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SET-2

# III B.TECH – I SEM EXAMINATIONS, NOVEMBER - 2010 PROCESS CONTROL INSTRUMENTATION (COMMON TO EIE, ICE)

**Time: 3hours** 

Max.Marks:80

#### Answer any FIVE questions All questions carry equal marks

- - -

- 1.a) Describe the output of a three mode controller for an assumed error variation. Discuss its features.
  - b) With an analytic expression of a PID control explain the effect of each mode on the output of the composite controller. [8+8]
- 2.a) Write a short note on following errors
  - i) IAE
- ii) ITAE
- iii) ISE
- b) Explain the importance of 1/4<sup>th</sup> decay ratio.

[8+8]

- 3. Illustrate with relevant graphs. The following methods of optimum settings from the plant response
  - a) Damped Oscillation method
  - b) Reaction-curve method.

[16]

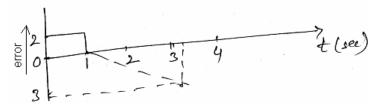
4. Explain the principle of a direct and reverse pneumatic actuator

[16]

- 5.a) Explain the flapper nozzle system with the help of its characteristic curves
  - b) Explain the following:
    - i) Quicle operating
    - ii) Linear
    - iii) Equal percentage characteristics of a control valve

[8+8]

- 6. Write the steps followed in choosing a valve for better control of flow and should be cost effective. [16]
- 7. Name five flow laws relating to fluids, heat and electricity and state these laws. [16]
- 8.a) A proportional controller has a gain of 3. Plot the controller output for the error given below fig1. If  $P_0 = 50\%$ . [ $P_0$  controller output with no error]



b) With neat sketches, explain the principle of integral control action

[10+6]

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SET-3

# III B.TECH – I SEM EXAMINATIONS, NOVEMBER - 2010 PROCESS CONTROL INSTRUMENTATION (COMMON TO EIE, ICE)

**Time: 3hours** 

Max.Marks:80

Answer any FIVE questions All questions carry equal marks

- - -

- 1. Illustrate with relevant graphs. The following methods of optimum settings from the plant response
  - a) Damped Oscillation method
  - b) Reaction-curve method.

[16]

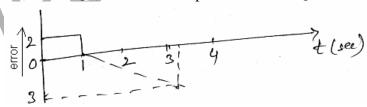
2. Explain the principle of a direct and reverse pneumatic actuator

[16]

- 3.a) Explain the flapper nozzle system with the help of its characteristic curves
  - b) Explain the following:
    - i) Quicle operating
    - ii) Linear
    - iii) Equal percentage characteristics of a control valve

[8+8]

- 4. Write the steps followed in choosing a valve for better control of flow and should be cost effective. [16]
- 5. Name five flow laws relating to fluids, heat and electricity and state these laws. [16]
- 6.a) A proportional controller has a gain of 3. Plot the controller output for the error given below fig1. If  $P_0 = 50\%$ . [ $P_0$  controller output with no error]



b) With neat sketches, explain the principle of integral control action

[10+6]

- 7.a) Describe the output of a three mode controller for an assumed error variation. Discuss its features.
  - b) With an analytic expression of a PID control explain the effect of each mode on the output of the composite controller. [8+8]
- 8.a) Write a short note on following errors
  - i) IAE
- ii) ITAE
- iii) ISE
- b) Explain the importance of 1/4<sup>th</sup> decay ratio.

[8+8]

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SET-4

# III B.TECH – I SEM EXAMINATIONS, NOVEMBER - 2010 PROCESS CONTROL INSTRUMENTATION (COMMON TO EIE, ICE)

**Time: 3hours** 

Max.Marks:80

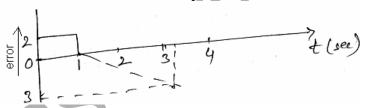
Answer any FIVE questions All questions carry equal marks

- - -

- 1.a) Explain the flapper nozzle system with the help of its characteristic curves
  - b) Explain the following:
    - i) Quicle operating
    - ii) Linear
    - iii) Equal percentage characteristics of a control valve

[8+8]

- 2. Write the steps followed in choosing a valve for better control of flow and should be cost effective. [16]
- 3. Name five flow laws relating to fluids, heat and electricity and state these laws. [16]
- 4.a) A proportional controller has a gain of 3. Plot the controller output for the error given below fig1. If  $P_0 = 50\%$ . [ $P_0$  controller output with no error]



b) With neat sketches, explain the principle of integral control action

[10+6]

- 5.a) Describe the output of a three mode controller for an assumed error variation. Discuss its features.
  - b) With an analytic expression of a PID control explain the effect of each mode on the output of the composite controller. [8+8]
- 6.a) Write a short note on following errors
  - i) IAE
- ii) ITAE
- iii) ISE
- b) Explain the importance of 1/4<sup>th</sup> decay ratio.

[8+8]

- 7. Illustrate with relevant graphs. The following methods of optimum settings from the plant response
  - a) Damped Oscillation method
  - b) Reaction-curve method.

[16]

8. Explain the principle of a direct and reverse pneumatic actuator

[16]

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